

- Junhao Xiao, one member of NuBot team, served to MSL community as an EC member. He has also served as a MSL TC member of RoboCup 2016 Leipzig, Germany, a member of MSL TC and OC of RoboCup 2015 Hefei, China, and local chair of RoboCup 2015 MSL.
- Huimin Lu, one member of NuBot team, served to MSL community as a member of TC and OC of RoboCup 2008 Suzhou, and he was also appointed as the local chair of RoboCup 2008 MSL. He was a member of TC of RoboCup 2011 Istanbul.
- Junchong Ma, one member of NuBot team, served to MSL community as a member of TC RoboCup 2017 Nagoya and RoboCup 2018 Montreal.
- Zhiqian Zhou, one member of NuBot team, served to MSL community as a member of OC RoboCup 2019 Sydney and TC RoboCup 2020.
- We build a dataset for robot detection which contained fully annotated images acquired from MSL competitions on a regular field. The dataset is publicly available at: <https://github.com/Abbyls/robocup-MSL-dataset>.
- We released the source code of our robots and a simulation system under an open source license. Particularly, this simulation system supports 3D simulation of the MSL competition between two teams, which has been employed in China Robot Competition since. Until 2020, 8 teams from China joined the competition and one team decides to join RoboCup MSL in the next few years. It can also be used for the research of multi-robot coordination control and the development of the RoboCup MSL community.